

Operational Manual

EDU2AE/HP_{RO}/TA

Torque range: 0.35-70 Nm



IDENTIFICATION DATA OF THE MANUFACTURER

KOLVER S.r.l.
VIA M. CORNER, 19/21
36016 THIENE (VI) ITALIA

IDENTIFICATION DATA OF THE PRODUCT

MODEL:	EDU2AE/HP _{RO} /TA
CODE:	034000/HPRO/TA

TECHNICAL DATA OF THE PRODUCT

FUSE: 3.15 A
DIMENSIONS: 195 x 170 x h110 mm WEIGHT: 2,4 Kg

DECLARATION OF CONFORMITY



KOLVER S.r.l. declares that the new tool here described: control unit model EDU 2AE is in conformity with the following standards and other normative documents:

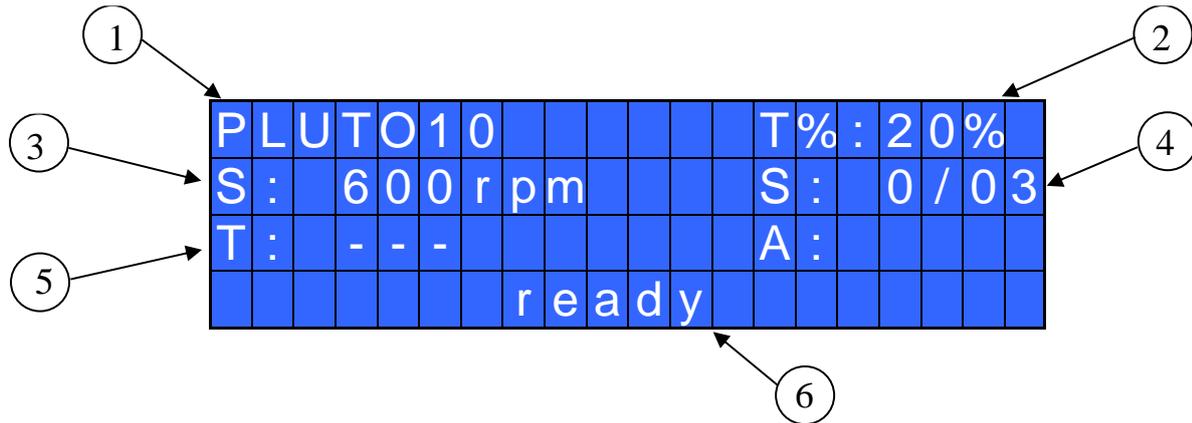
2006/42/CE, LVD 2014/35/UE, EMCD 2014/30/UE, EN 62841-2-2:2014, EN 62841-1: 2015, EN 60204-1, EN 61000-6-2, EN 61000-6-4.

It is also in conformity with RoHS III normative (2011/65/UE and following 2015/863).

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Position: General Manager
Person authorized to compile the technical file in Kolver.

Thiene, January 1st 2023

Giovanni Colasante



- 1- Screwdriver model
- 2- Pre-set torque level (percentage)
- 3- Selected speed
- 4- Screw count: fastened screws/total screws
- 5- Reached torque level Sin Nm, in.lbs or kgf.cm.
- 6- Status bar (waiting, screwing, errors, etc...)



To enter the menu press **ESC** for 2 seconds.

Select the line by pressing **↑** or **↓** then press **OK** (the symbol **▶** will turn into **■**). Press **↑** or **↓** to select the required value and then confirm through **OK** (or **ESC** if you don't want to save the value).

The selected value will be immediately operational, even if you are still in the menu screen. Repeat these operations for all the parameters you wish to set and then push **ESC** to return to the main screen.

FRONT PANEL LED:



GREEN LED: *Screw OK.*

YELLOW LED: *Program End*

RED LED: error.

MENU

-	-	-	-	-	M	A	I	N	-	M	E	N	U	-	-	-	-	-
O	K		c	h	a	n	g	e			E	S	C		q	u	i	t
▶	P	r	o	g	r	a	m		s	e	t	t	i	n	g			
	U	n	i	t		o	p	t	i	o	n	s						

Program setting: It indicates the menu section where you can set or modify the fastening parameters.

Unit Options: It indicates the menu section where you can set the language, check the versions of the boards, the cycles done, set the password, set the unit of measure, the buttons and the screwdriver detect mode.

Program setting

-	-	-	-	-	-	-	-	M	E	N	U	-	-	-	-	-	-	-			
O	K		c	h	a	n	g	e			E	S	C		q	u	i	t			
▶	1)	S	c	r	e	w	s		n	u	m	.	:				1			
	2)	M	o	d	e	l	:							P	L	U	T	O	1	0

1) Screws number: EDU2AE/HPRP/TA can act as screw counter. You can set the number of screws from 1 to 99. To disable the function select OFF by pressing  as many times as needed.

If the number of correct screws is equal to the number of set screws “Program end” will appear on the status bar and the yellow led will light up. If the OK/ESC function is disabled (see points 7 and 8 of Unit Options Menu), “Program end” will automatically disappear at next screwing or when you enter the menu. Otherwise, press OK at the end of each program.

2) Model: you can select the screwdriver to be used. Your choice will automatically change the default settings. It’s important to select the correct model you’re going to use since many parameters regarding the motor software are specific for every single model.

Also in the # mode, if the *Model Detect* is set on auto and no screwdriver is connected, it won’t be possible to set any torque value or speed.

-	-	-	-	-	-	-	-	M	E	N	U	-	-	-	-	-	-	-		
	3)	R	a	m	p	:								0	.	3	s		
▶	4)	T	o	r	q	u	e	:						1	0	%			
	5)	C	o	m	p	e	n	s	:					0	.	0	0	N	m

3) Ramp: You can select the slow start time (acceleration) from 0.2 to 3.0 sec. This option is only available for the screwing phase, while during the unscrewing phase the ramp time is always 0.2 sec. We suggest using this option with self-tapping screws.

ATTENTION: Reaching the torque while the ramp is still on could give as result a different torque level from the one that results when the ramp is over. This is due to the motor acceleration.

Reaching the torque while the ramp is still on will activate the “screw OK” signal anyway (this option is useful if you need to tighten screws that are already tightened, the so called “double hit”).

On the other hand, if you wish to see an error signal during the preset torque in the ramp phase, you can change the minimum time by setting value which is equal or superior to the ramp value (see point 8).

4) Torque: you can select the desired torque as a percentage of the torque range of the selected screwdriver. For example, for a Pluto10, a 50% setting will result in a torque in the area of 4.5 Nm. The torque range is always referred to the MAX speed. In case you're not working at maximum speed, the torque range will progressively lower in order to avoid motor stalling. If the torque level is reached correctly, it will be showed on the display and you will hear a beep sound, too.
Such torque level is indicated as “ T: ..% ” on the main screen.

5) Compens – Compensation: This function allows an increase or decrease of the displayed torque after calibration. The available range is from 0 to ±55 Nm. For example: after calibration (see Torque calibration) you make a screwing on your assembly and compare the value you see on the main screen display with the value you see on a torque tester (for example a mini-K or a K model). Let's say you notice that the torque displayed in the unit EDU 2AE is +0.2 Nm higher than the value indicated on the tester (which is the right one). In this case you change this value by setting -0.2 Nm so that the value on the screen will be the same as the value on the tester. If it's lower than 0.3 Nm, you need to set +0.3 Nm and so on.

-	-	-	-	-	-	-	-	MENU	-	-	-	-	-	-	-					
6)	Tm		F	a	s	t		s	p	d	:			o	f	f			
→	7)	F	a	s	t		s	p	d		a	n	g	:		o	f	f	
8)	F	a	s	t		s	p	d	:								o	f	f

6) TM Fast Spd (Time Fast Speed): It indicates how long the screwdriver should turn at the FAST SPEED speed (see point 8) before switching to “pre-set speed” (lower speed). The “pre-set speed” is the speed set at point 9. This FAST SPEED time can be set from 0.3 to 10.0 sec.
To disable the function press ↵ until you get to OFF. In this case the screwdriver will automatically start at pre-set speed.
Once the timed fast phase has been set, it will not be possible to set an angled fast phase.

CAUTION: The aim of the FAST SPEED is only to speed up the approach time in case of long screws. Reaching the torque at higher speed will result in inaccurate torque output. To avoid inaccurate torque values we suggest first to set a shorter time, and then increase it.
Torque reached during the FAST SPEED won't activate the torque signal and the message “Error FAST SPEED” will be displayed on the main screen and 2 beep sounds. The red led will turn on, too.

7) Angle Fast Speed: it indicates the angle the screwdriver should reach at the FAST SPEED speed (see point 8) before switching to “pre-set speed” (see point 9).

8) Fast spd (Fast Speed): You can select the speed of the screwdriver during the FAST SPEED. It can be set between max speed and the Final Speed (see point 9).
This function is available only if the Time Fast Speed and/or the Angle Fast Speed is ON.

-	-	-	-	-	-	-	-	MENU	-	-	-	-	-	-	-				
9)	F	i	n	a	l		s	p	d	:		6	0	0	r	p	m	
→	10)	R	u	n	t	i	m	e	:			2	0	.	0	s		
11)	M	i	n		t	i	m	e	:							o	f	f

9) Final Spd (Final Speed): You can select any speed value of the screwdriver between the maximum and the minimum specific speed of every single screwdriver (see table with technical data).

10) Run time: You can set the time of a tightening, from OFF to 20.0 sec. When the pre-set time has been reached, it results in a torque signal.

The couple reached during this time results in a signal of *Correct screw*. If the correct screw signal is not required, set the Minimum time up to a value of 'Minimum Time -0.1sec'.

ATTENTION: Max Time must be set at 20.0 sec.

11) Min Time - Minimum Time: You can set this time from 0.1 sec to 'Max time - 0.1s'. To disable the function select OFF by pressing \downarrow as many times as needed. (Min time = 0).

Torque reached below the minimum time won't activate the torque signal and will result in an error signal. "Below minimum time" will be displayed on the status bar and the red led will light up. You will hear two beep sounds, too.

-	-	-	-	-	-	-	-	MENU	-	-	-	-	-	-				
1	2)	M	a	x	t	i	m	e	:			2	0	.	0	s	
▶	1	3)	P	r	e	R	e	v	:						o	f	f
1	4)	A	u	t	o	R	e	v	:			2	0	.	0	s	

12) Max time - Maximum time: You can select the maximum time of tightening. You can set from 'Min time + 0.1s' to 20.0 sec.

You also can set the Maximum time to OFF by pressing the \uparrow button when you have reached the value of 20.0s. In this case the screwdriver turns without any time limit.

ATTENTION: If torque isn't reached by the maximum time, the screwdriver will stop. "Over maximum time" will be displayed on the status bar and the red led will light up. You will hear two beep sounds, too.

13) Pre-Rev. (Pre-reverse): You can set a reverse before a screwing.

Time can set from OFF to 20.0 sec.

ATTENTION: Pre-reverse speed and torque are the same as Auto Rev.

14) Auto Rev: This option will automatically start a reverse after a torque reached/ correct screw signal. You can set time from 0.1 to 20.0 sec.

To disable the function select OFF by pressing \downarrow as many times as needed.

ATTENTION: During the reverse, it is necessary to keep the lever or the start signal pressed as long as it won't stop. "Correct screw" will be displayed on the status bar and a green led will light up. You will hear one beep sound, too. In case the lever is released before the end of the reverse, "unfinished screw" will be displayed and a red led will light up. You will hear two beep sounds, too.

-	-	-	-	-	MENU	-	-	PR: 1	-	-	-	-	-					
1	5)	R	e	v	s	p	d	:			6	0	0	r	p	m	
▶	1	6)	R	e	v	t	o	r	q	u	e	:			M	A	X
1	7)	P	V	t	o	r	q	u	e	:					o	f	f

15) Rev speed – Reverse speed: You can select any reverse speed value of the screwdriver between the maximum and the minimum specific speed of every single screwdriver (see table with technical data).

16) Rev torque – Unscrewing torque: You can select the desired torque as a percentage of the torque range of the selected screwdriver (see point 2). If the torque is set on MAX, the unscrewing torque is about 20% higher than the possible maximum torque, so that it is always possible to unscrew the tightened screw (we suggest leaving this function on in normal use). If the setting is from MIN to 99% the unscrewing torque with the same percentage will be equal to the settings of the screwing phase.

ATTENTION: If you're using open-end wrenches, the unscrewing torque has to be set to MIN value in order to bring the wrench back to the correct position.

17) PV torque: Period of time in which the screwdriver works at maximum torque before switching to the torque that has been set by the user. You can set time from 0.1 to 10.0 sec. To disable the function select OFF by pressing  as many times as needed.

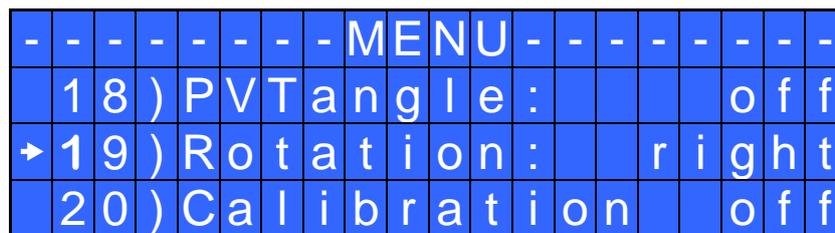
This function overlaps other time settings (fast speed, ramp time, minimum time, maximum time) from the motor start on.

Once the timed PV torque phase has been set, it will not be possible to set an angled Prevailing torque phase.

ATTENTION: This function is useful for applications where the prevailing torque is higher than the final torque (for example trilobal screws or locknuts).

Please use this function with utmost attention because an incorrect use can damage both the assembly and the screwdriver.

Torques reached during the max torque time won't activate the torque signal. "PV Error" will be displayed and the red led will light up. You will hear two beep sounds, too.



18) PVTangle – Prevailing Angle Torque: it indicates the angle that the screwdriver must reach at the maximum torque and then continue at the pre-set torque. The angle can only be set if the "TORQUE/LEVER" mode (23) is active, therefore when the lever is pressed, the screwdriver will turn at maximum torque.

This function overlaps with the other time/angle settings (fast phase, ramp, minimum time, maximum time) starting from the motor start.

Once the Prevailing Angle torque has been set, it will not be possible to set a PV Torque.

To disable the function, enter an angle equal to 0°. In this case the screwdriver will apply the torque set by the user.

ATTENTION: This function is useful for applications where the prevailing torque is higher than the final torque (for example trilobal screws or locknuts).

Please use this function with utmost attention because an incorrect use can damage both the assembly and the screwdriver.

Torques reached during the max torque time won't activate the torque signal. "PV Error" will be displayed and the red led will light up. You will hear two beep sounds, too.

19) Rotation: You can choose between right tightening (standard screws) or left tightening (left threaded screws). All the other functions will adapt to the selected direction of rotation.

20) Calibration: ON allows to see the torque value on the main screen. OFF doesn't show the torque value. (To modify the calibration parameters see paragraph Torque calibration).

-	-	-	-	-	-	-	-	M	E	N	U	-	-	-	-	-	-	-		
2	1)	T	o	r	q		m	i	n	:		0	.	0	0	N	m		
→	2	2)	T	o	r	q		m	a	x	:		2	0	.	0	0	N	m
2	3)	F	u	n	c		T	&	A	:							o	f	f

21) Torq min – Minimum torque: The minimum torque and maximum torque options allow the user to set the acceptable torque range for each single application. When the reached torque is inside this range, “tightening OK” will be displayed on the status bar and the green led will light up. If the reached torque is outside this range the messages “error minimum torque” or “error maximum torque” will be displayed. You can set the torque range from 0 to 40 Nm at intervals of 0.01 Nm.

The minimum torque option allows to set the lowest value of the torque range and it’s on if calibration is 'ON'. If calibration is 'OFF' the minimum torque value automatically sets on 0 Nm.

22) Torq Max – Maximum Torque: The minimum torque and maximum torque options allow the user to set the acceptable torque range for the single application. When the reached torque is inside this range, “right screwing” will be displayed on the status bar and the green led will light up. The messages “below minimum torque” or “over maximum torque” will be displayed if the reached torque is outside this range. You can set the torque range from 0 to 55 Nm at intervals of 0.01 Nm.

The maximum torque option allows to set the highest value of the torque range and it’s on if the calibration is 'ON'.

23) Func T&A–T&A function mode: You can activate the Torque & Angle function. Set OFF when you don’t need this function. When you set ON you can choose among six working conditions (see T&A specific instructions).

-	-	-	-	-	-	-	-	M	E	N	U	-	-	-	-	-	-	-
2	4)	S	t	a	r	t	i	n	g		T	o	r	:	-	-	-
→	2	5)	A	n	g	.		m	i	n	:				-	-	-
2	6)	A	n	g	.		m	a	x	:				-	-	-	

24) Starting Tor – Starting torque: If T&A option is set on Tor mode (See T&A paragraph), you can set the torque threshold the angle starts to be read from. When T&A is set on angle mode (see T&A paragraph), you can set the torque threshold the angle starts to be carried out from.

In # mode, the torque threshold must be included in the range of values relating to the pre-set speed and model.

25) Ang. min – Minimum angle: Minimum angle threshold. You can set it when T&A is set on Tor, T/in or T/lv (see T&A specific instructions). The minimum angle the operator can set is 5°.

26) Ang. max - Maximum angle: Maximum angle threshold. You can set it when T&A is set on Tor, T/in or T/lv (see T&A specific instructions). The maximum angle the operator can set is 29999°.

When T&A is set on Ang., A/in or A/lv mode, maximum angle corresponds to the angle that has to be carried out.

Unit Options

-	-	-	-	O	P	T	I	O	N	S	-	M	E	N	U	-	-	-	-
OK		c	h	a	n	g	e				ESC		q	u	i	t			
→	1)	L	a	n	g	u	a	g	e	:								EN
	2)	V	e	r	s	i	o	n	s									

1) Language: This option allows to select among 4 languages: English, French, German, Italian, Spanish and Portuguese.

2) Versions: in this screen you can see the versions of boards mounted inside the unit.

-	-	-	-	O	P	T	I	O	N	S	-	M	E	N	U	-	-	-	-
	3)	C	y	c	l	e	s	:		0	0	0	0	0	0	0	0	0
→	4)	C	h	a	n	g	e		p	a	s	s	w	o	r	d		
	5)	P	a	s	s	w	o	r	d									

3) Cycles - Number of total screwing/errors done which have been carried out: It shows the number of fastened screws and occurred errors. This number can't be modified.

4) Change password: You can change password (see point 5).

5) Password: If YES, you will be asked for the password to enter the menu. Otherwise select NO.

ATTENTION: Password is only asked to enter the menu for the first time after switching the unit on. The default password is: 0000.

-	-	-	-	O	P	T	I	O	N	S	-	M	E	N	U	-	-	-	-
	6)	U	n	i	t	:												Nm
→	7)	P	r	e	s	s		OK	:									o f f
	8)	P	r	e	s	s		ESC	:									o f f

6) Unit: You can choose between the following units of measurements: Nm, in.lbs and kgf.cm.

7) Press OK: when ON, press OK at the end of each screwing.
When OFF, the control unit resets automatically after a screwing.

8) Press ESC: when ON, press ESC to reset the control unit.
When OFF, the control unit resets automatically after an error signal.

-	-	-	-	O	P	T	I	O	N	S	-	M	E	N	U	-	-	-	-	
	8)	P	r	e	s	s	E	S	C	:							o	f	f
	▶	9)	R	i	l	e	v	.	m	o	d	e	l	.	:	A	u	t	o

9) Model Detect: this function allows you to enable or disable automatic screwdriver recognition. If set to Auto, the unit recognizes and sets the screwdriver autonomously. In case of the screwdriver is not connected, the unit shows the warning "Connect screwdriver". When you connect a screwdriver different from the previous one or after formatting the unit (or on first use), the warning "Change model?" and the user can select "No" or "Yes". At the same time, the scrolling notice "All program settings will be reset" will be displayed to underline the fact that if "Yes" is selected, the torque, speed, etc. settings will be displayed. related to the previously connected screwdriver model will be lost. In the latter case, the new connected screwdriver will be set and the relative default values for torque and speed will be loaded. If the user selects "No" and leaves the screwdriver connected, the warning "Connect right model" which is the one set in the "Model" function of the relevant program, tightening is not allowed. In this mode it is not possible to manually set a screwdriver model. If there is no screwdriver connected to the unit, the display shows ---- instead of the model and torque. In case of an unrecognizable screwdriver is connected, the unit will not show any model and tightening will not be allowed.

If this function is set in **manual**, automatic model recognition is disabled and the user will select the desired screwdriver model through the Program menu). After formatting the unit or its first use with the Model Detection setting in Manual, the warning "Select Model" will appear on the display.

In both operating modes (**Auto** and **Manual**), if in field 3) of the Program menu you are in the "Model: ----" status, it is not possible to change the values relating to the torque and speed in tightening (unscrewing).

ATTENTION: with the model detection set to Auto in case of recognition malfunctions caused for example by external interferences, set the model detection in Manual and select the desired screwdriver.

IMPORTANT: the "Model Detection" function is active only in the inline and ANG models.

TORQUE CALIBRATION

The torque calibration function allows to view the torque value in Nm or in.lbs or kgf.cm directly on the display of the control unit.

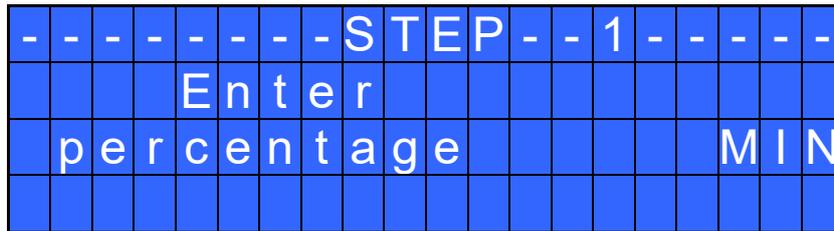
IMPORTANT: You need a torque tester to proceed, either with static transducer (model minik or K) or with rotary transducer (model minik-e).

CALIBRATION PROCESS:

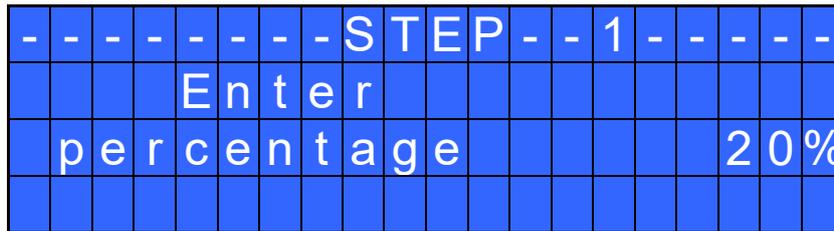
1. Select Calibration at point 20 of the menu and press OK.
2. The following screen will appear on the display:

-	-	-	-	-	-	-	-	M	E	N	U	-	-	-	-	-	-	-	-	
	1	9)	C	a	l	i	b	r	a	t	i	o	n	:				o	n

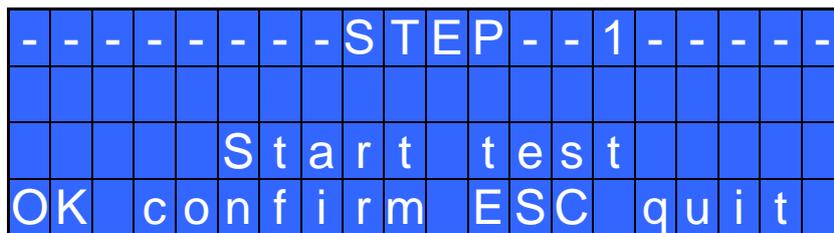
3. Press OK to confirm. If you choose OFF, calibration will be interrupted and no torque value will be displayed. You choose ON, calibration will continue and the following screen will be displayed:



4. Set the first torque level at 20% percentage by pressing \hat{u} .



5. Press OK. You will see:

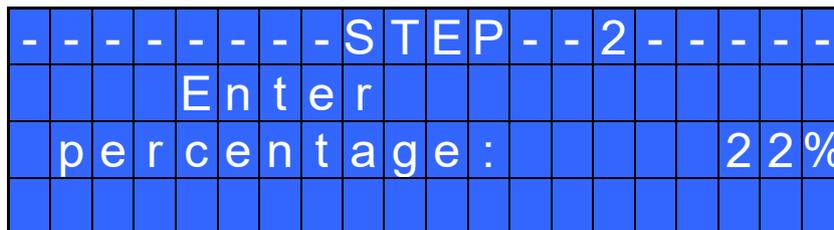


Complete a screwing cycle on the mini k5 and take note of torque value.

6. Press OK, then the display will show:



Set the torque value by pressing \hat{u} and press OK again to save. You will see:



7. Set the percentage of the second torque to 30% by pressing \hat{u} and press OK.

8. Repeat the procedures described on points 4 and 5.

9. When calibration ends, "Setting end" will be displayed. You will hear two beep sounds, too. Now you are ready to work and see the correct torque on the display.

WARNING:

- Calibration values will be referred to the parameters of the control unit which are set during calibration, i.e. if you modify speed or torque, the unit will need to be recalibrated. During calibration when a screwing is not carried out correctly or if for any reason you're not sure of the torque value it is possible to repeat it. A wrong screwing can affect the precision of the calibration.
- Calibration is carried out for two torque levels optionally chosen. The minimum calibration interval is 2% (example: if I have to work at 50%, I can calibrate at 49% and 51%). In this case, if for any reasons I need to work at torque percentages which are lower or higher than the min-max ones set during the calibration, they will be analyzed and displayed anyway but since they won't be based on effective data the torque value displayed may be not accurate.
- During calibration it is not possible to go back to the previous screen. Press ESC to stop calibration and then repeat the screwing cycles.

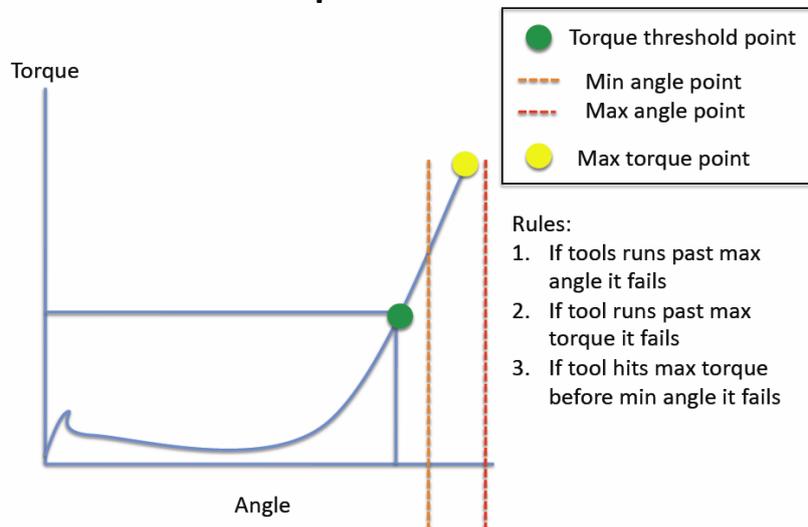
USE OF T&A (Torque & Angle)

Choose the T & A mode (see point 23: Modify function on the program menu)

It is possible to set 6 different modes:

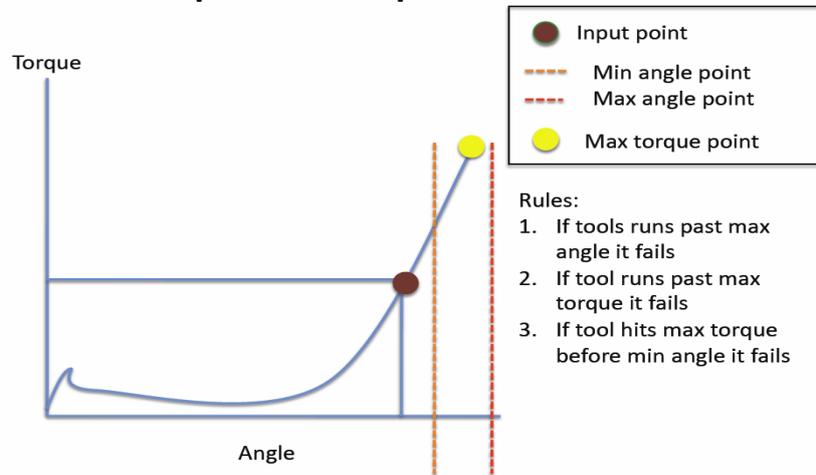
- ✦ **TORQUE (Torque):** It's the most common use mode. The control unit shows the tightening torque and the torque starting from a certain torque percentage (threshold torque, see point 24). If the final torque and angle values are within the preset minimum and maximum values, the screw is correctly tightened. If the torque and/or angle are outside the preset values, the screw will be considered as incorrectly tightened. In this case the red led will light up and the message "Error Max (Min) Angle" or "Error Max (Min) Torque" will be displayed.

Torque mode



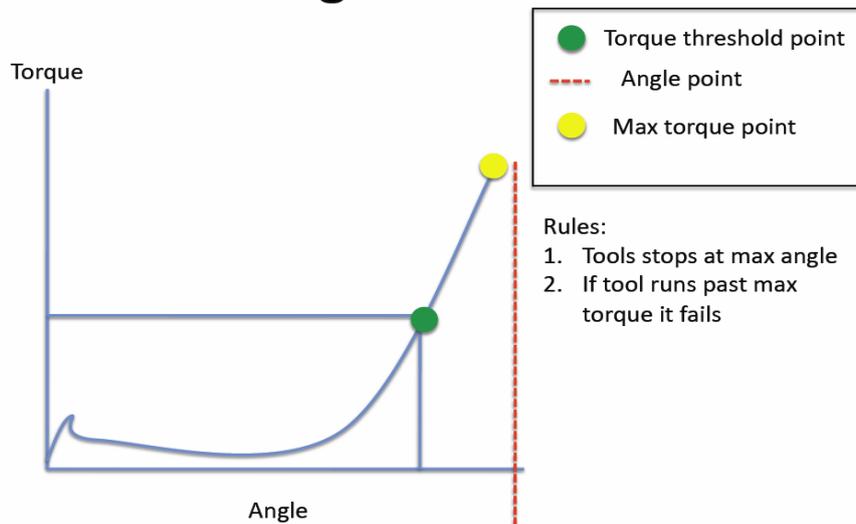
- ✦ TORQUE/INPUT (T/IN): It corresponds to *Torque* mode, except for the threshold torque which can't be set by the operator: in fact the value is the result of an external impulse through a proper contact (see paragraph "connections"). It can be very useful if the operator wants the control unit to start counting the angle from a position which is indicated by a precision instrument.

Input/Torque mode



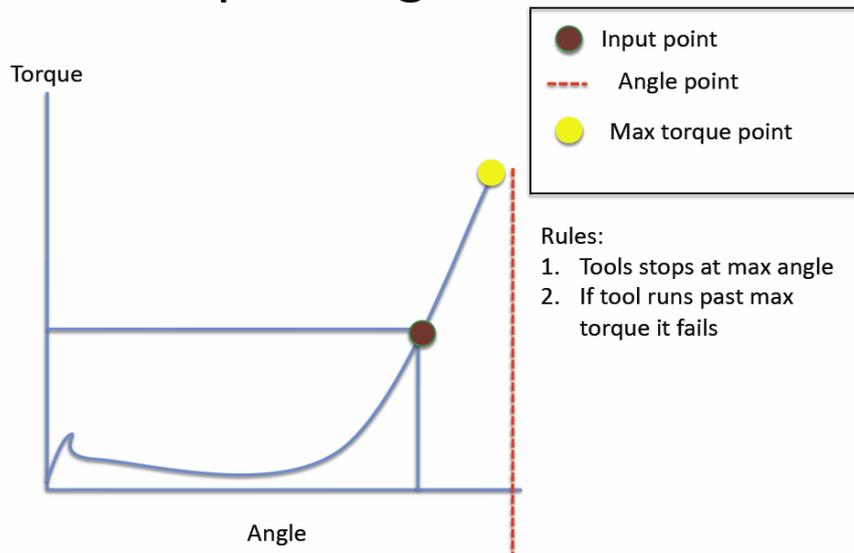
- ✦ TORQUE/LEVER (T/LV): No threshold is preset by the operator: the angle value that appears on the display corresponds to the angle that is carried out starting from the moment in which the lever is pressed until the torque is reached.
- ✦ ANGLE (Ang.): This mode gives priority to the angle to be reached. The value is measured starting from a tightening torque percentage. Starting from the preset threshold torque (see point 24) the system will start counting the degrees and when the preset angle is reached the screwdriver will stop. If the preset angle is reached the screw will be considered as correctly tightened, the green led will light up and the message "*tightening OK*" will be displayed on the status bar. If the screwdriver stops before reaching the preset angle the tightening will be considered not ok, the red led will light up and the message "error angle not reached" will be displayed on the status bar. Therefore it's very important to set a torque value which is sufficiently higher than the threshold value (line 4), so that the set value is reached before the screwdriver stops because of the reached torque.

Angle mode



- ▲ ANGLE/INPUT (A/IN): The threshold can't be set by the operator: in fact the value is the result of an external impulse through a proper contact (see paragraph "connections"). This function can be very useful if the operator wants the screw to rotate a certain number of degrees after reaching a position indicated by a precision instrument.

Input/Angle mode



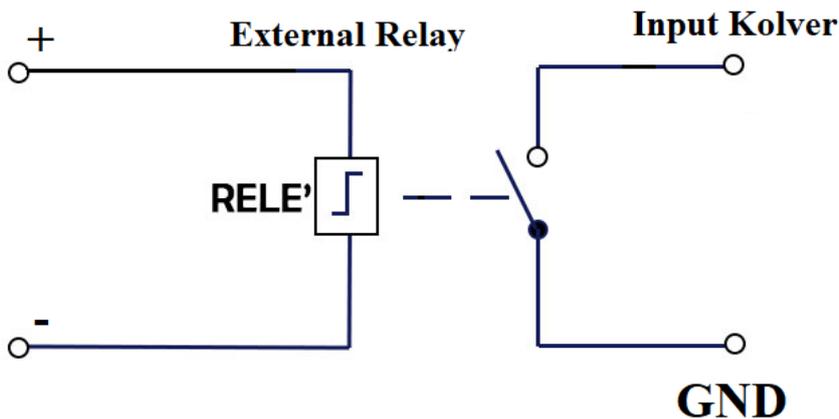
- ▲ ANGLE/LEVER (A/LV): the threshold torque value can't be set by the operator and the angle value that appears on the display corresponds to the angle that is carried out starting from the moment in which the lever is pressed. The angle has to be set in the "Ang. max ". If the lever is released before reaching the set angle, the error "Error ang not OK" will be displayed.

INTERPRETATION OF ACOUSTIC SIGNALS

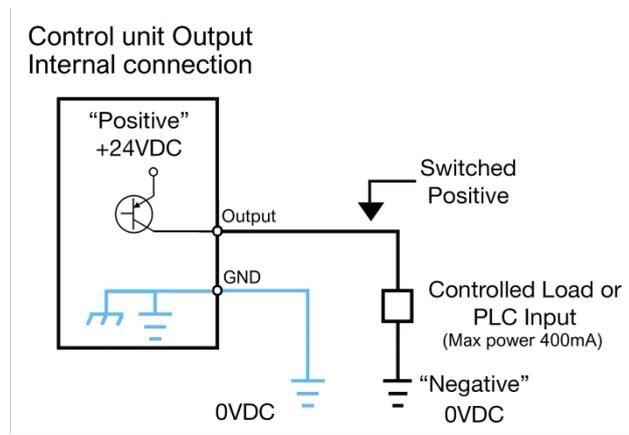
The control unit emits sounds which help you understand if the screwing has been carried out correctly or not. When the torque is reached meeting all the parameters set, the control unit utters a 0.5 sec beep as confirmation. In case of Program End, the unit will utter other two beeps. Instead, torque reached under min time, during the Ramp time or under the Fast speed (see error signals on the display) will cause the control unit to utter three beep sounds.

I/O CONNECTIONS

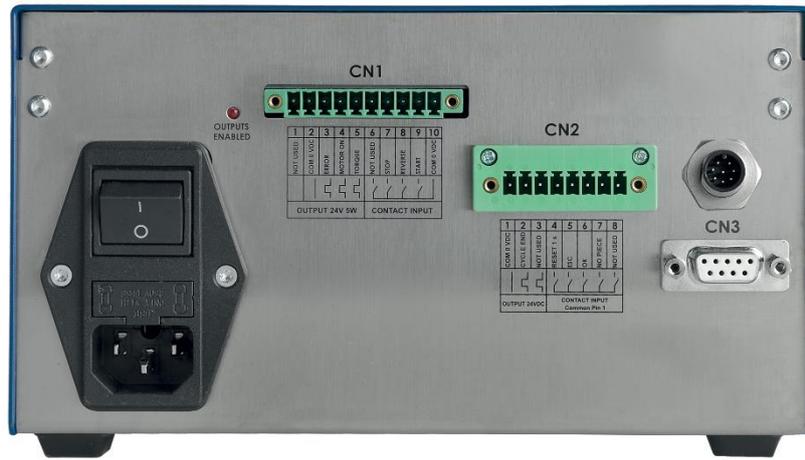
EDU 2AE control unit series have connectors placed on the back panel. These connectors allow to enable functions through inputs and to take signals through outputs. The inputs are activated by connecting them to ground. A positive voltage must NEVER be brought to these inputs. Bringing 24V to the unit inputs could damage the inputs themselves. As seen from the picture below, to enable the inputs it is recommended to bring a clean contact by using a relay or a simple switch or button.



As for the outputs, they are all PNP type with active function. On each pin you will have 24V DC.

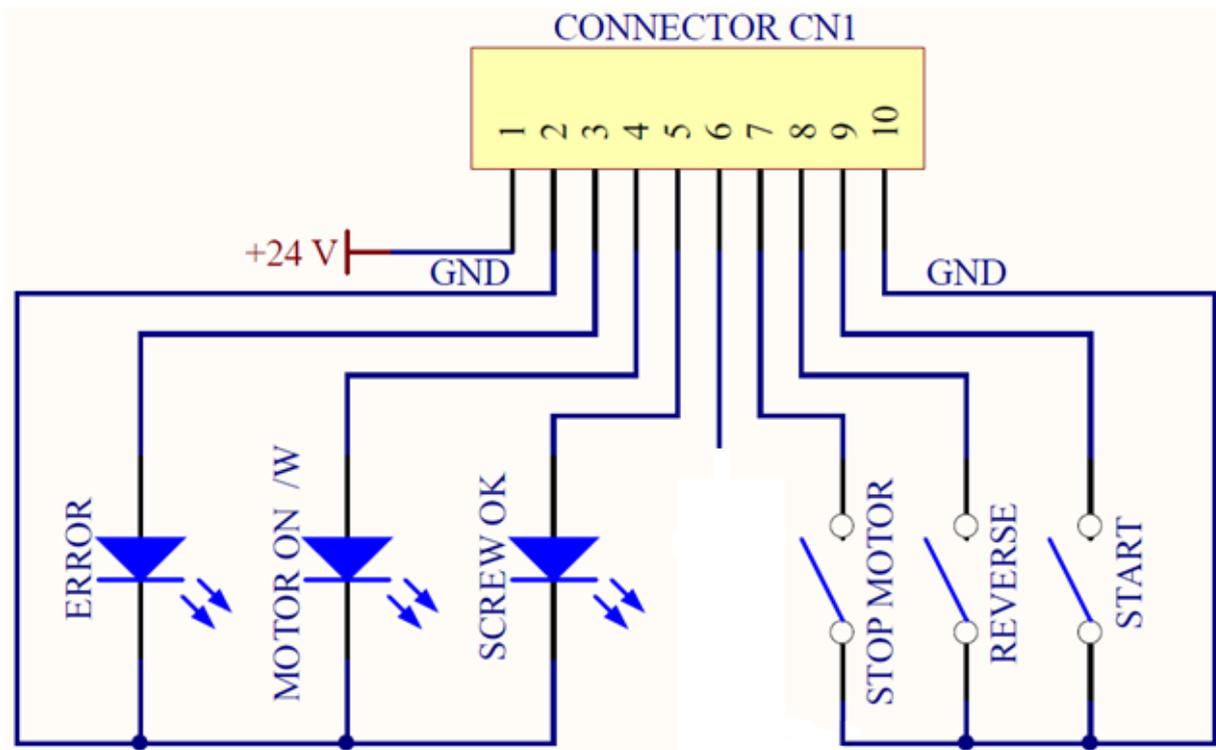


These pins can be used directly connected to PNP inputs (PLC) or used to turn on LEDs, buzzers or other devices with 24V power supply. The maximum total power of the outputs is about 400mA. Using inductive loads such as relays or other loads with an initial consumption peak greater than 400mA will send all outputs to protection, displaying the message "output disable". To restore the outputs after a protection, turn off and turn on the unit again.



- CN1 CONNECTOR – 10 pin:

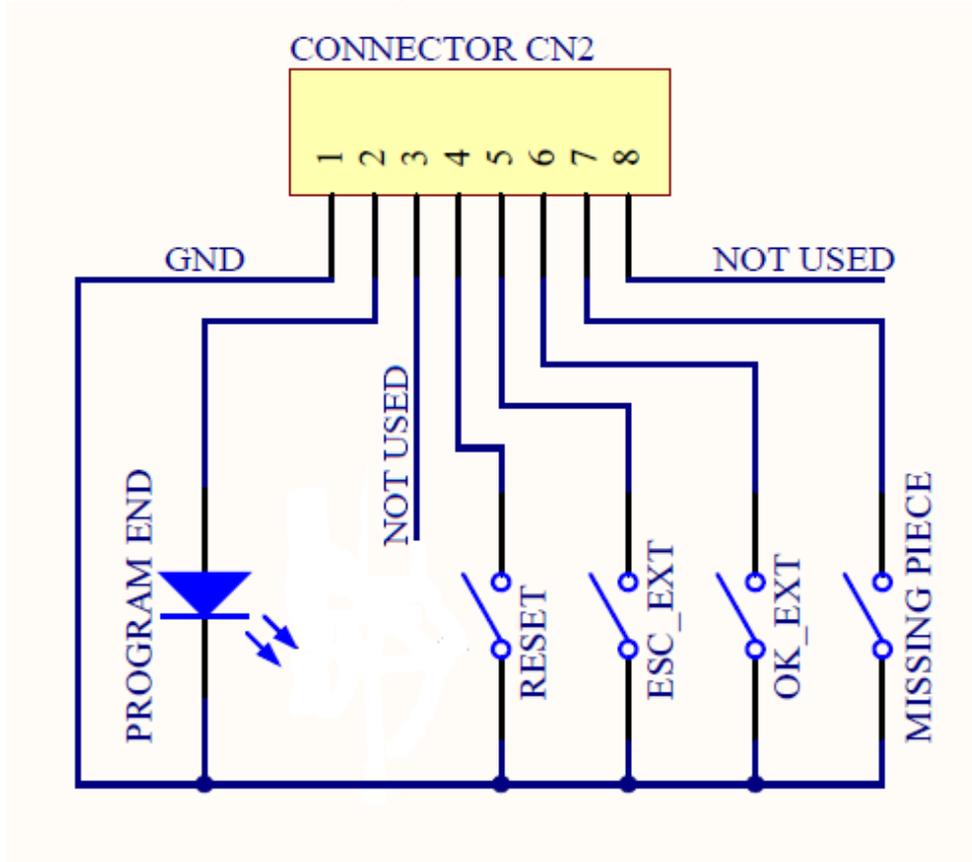
On the back panel, in all the EDU 2AE units, there is a 10 pin I/O connector.



PIN	NAME	FUNCTION
OUTPUT		
1	+24V	+24V voltage protected. The maximum current consumption is 400mA. CAN NOT BE USED TO POWER EXTERNAL DEVICES.
2	GND	Common pin. Signals must be taken between this pin (0VDC) and the respective signal pins.
3	ERROR	Error signal: it activates every time an error occurs. The red led on the front panel will switch on. Signal is 24V.
4	MOTOR ON (W)	It activates when the motor turns during screwing. Signal is 24V.
5	SCREW OK	Correct screw signal. The green led on the front panel will switch on. Signal is 24V.
INPUT		

6	NOT USED	Not used
7	STOP MOTOR	Remote motor stop. If it's activated the message "STOP MOTOR ON" appears on the display. The motor will stop and won't start working again as long as the contact is closed.
8	REVERSE	Remote motor start with torque control while unscrewing.
9	START	Remote start with torque control while screwing.
10	GND	Common pin. Signals must be taken between this pin and the respective signal pins.

- CN2 CONNECTOR – 8 pin:



PIN	NAME	FUNCTION
OUTPUT		
1	GND	Common pin for any input and output. By closing the contact between pin 1 and any of the other pins to start the function you need. This pin is connected to 0VDC and to the ground.
2	PROGRAM END	It activates at the end of each program.
3		Not used.
INPUT		
4	RESET	If pressed for at least 1 sec, it resets the program you are working in.
5	ESC_EXT	If enabled, (see point 9: OK/ESC), remote ESC key function to reset errors.
6	OK_EXT	If enabled, (see point 9: OK/ESC), remote OK key function to confirm program end.
7	MISSING PIECE	If enabled, it stops the motor, it enables the error signal and "Error missing piece" is displayed on the status bar.
8		Not used.

ATTENTION: Output signals are protected from an appropriate circuit. Overload of the available signals (> 450 mA) or short circuit will result in the stop of the unit. To re-activate signals, it is necessary to switch off the unit for 5-6 seconds, check connections and output loads then switch the unit on.

- CN3 CONNECTOR (9 pin serial connector – female)

PIN	NAME	FUNCTION
1	+15 Vcc	Not used.
2	TX	Serial transmission.
5	GND	Common pin for any input. Signals must be taken between this pin (GND) and the other pins of this connector depending on the signal you want to be printed.

CORRECT SCREWS ON STATUS BAR

“Screw OK” is displayed on the status bar.	The tool has performed a correct screwing, that is when all the settings have been fulfilled.
On the status bar it will display “Angle OK”.	A correct screwing has been performed, reaching the pre-set angle.
“Run Time OK” is displayed on the status bar.	The tool has performed a correct screwing, that is when all the settings have been fulfilled.
“Rev. Torque OK” is displayed on the status bar.	The tool has performed a correct screwing, that is when all the settings have been fulfilled.

TROUBLE SHOOTING

ERROR	PROBLEM	SOLUTION
0	“Waiting connection” doesn’t turn into “system ready” after it’s been switched on.	Contact your nearest Kolver dealer.
1	“Error Torque Control” is displayed on the status bar	Make a new screw. If the error persists, change the torque and speed settings.
2	“Error fast speed” is displayed on the status bar (the torque signal is displayed during the fast speed).	If <i>Press ESC</i> function is ON, press ESC for a new screw; if it’s OFF it automatically resets next time you screw.

3	“ <i>Rev. incomplete</i> ” is displayed on the status bar (the displayed torque signal is correct but the set unscrewing is not complete).	
	“ <i>Pre-reverse incompl.</i> ” is displayed on the status bar (the lever has been released before the Pre-Rev. has been completed).	
5	“Under min time” is displayed on the status bar (the torque signal is displayed below the set minimum time).	
6	“Over maximum time” is displayed on the status bar (the torque signal is displayed over the set maximum time).	
7	“ <i>Error PV torque</i> ” is displayed on the status bar (the torque signal is displayed inside the set maximum time).	
8	“ <i>Below min torque</i> ” is displayed on the status bar (the torque signal is displayed below the set minimum time).	
9	“ <i>Over max torque</i> ” is displayed on the status bar (the torque signal is displayed over the set maximum time).	
10	“ <i>Error min angle</i> ” is displayed on the status bar (the torque signal is displayed below the set minimum angle).	
11	“ <i>Error max angle</i> ” is displayed on the status bar (The max preset angle has been reached. Only available in Tor, T/lv and T/in mode).	
12	“ <i>Error angle not OK</i> ” is displayed on the status bar (The preset angle hasn’t been reached. Only available in Ang., A/lv and A/in mode).	
13	“ <i>Warning! No piece</i> ” is displayed on the status bar (The “missing piece” contact is enabled).	-check contact 2 on the CN2 connector
14	“ <i>Compensation error</i> ” is displayed on the status bar (the torque value is negative – this is due to an excessively high negative compensation value)	- Set a higher/lower compensation value.
15	“ <i>Reverse torque error</i> ” is displayed on the status bar (The torque signal is displayed while loosening, but only if it’s set on “max”).	- The screwdriver couldn’t loosen - Avoid motor stalling - Loosening too heavy
16	“Protection 12A” is displayed on the status bar (it happens when current on mosfets of bridge H is > 12 A for at least 1 sec).	- Reduce cycle rate and check settings. - Avoid motor stalling. - Unscrewing too heavy. - Joint too soft.
17	“ <i>Protection 14p5A</i> ” is displayed on the status bar (it happens when current on mosfets of bridge H is > 14.5 A for at least 800 ms).	- Reduce cycle rate and check settings. - Avoid motor stalling. - Unscrewing too heavy. - Joint too soft.

18	“Protection 15A” is displayed on the status bar (it happens when current on mosfets of bridge H is > 15 A for at least 500 ms).	<ul style="list-style-type: none"> - Reduce cycle rate and check settings. - Avoid motor stalling. - Unscrewing too heavy.
19	“OUTPUT DISABLED” is displayed on the status bar. It is on the protection of the output signals exceeding the maximum load (400mA).	<ul style="list-style-type: none"> - Check that the load does not exceed the max (400mA) - To reset, restart the unit.

ATTENTION: IF THE OK/ESC OPTION IS DISABLED, ERRORS RESET AT THE FOLLOWING SCREWING/PROGRAM. OTHERWISE PRESS ESC. IF THE PROBLEM PERSISTS, PLEASE CONTACT YOUR NEAREST KOLVER DEALER.

SERIAL PORT:

EDU 2AE/HPRO/TA control unit is supplied with a serial 9 pin male connector. In this way you can print the results of each screwing. The transmission characteristics are the following:

9600 (bits per second), 8 (data bits), n (no parity), 1 (bits stop 1).

Connection pin: PIN 2 = TX, PIN 5 = GND

The print string is the following:

<i>RESULT</i>	<i>MODEL</i>	<i>TORQUE%</i>	<i>SPEED</i>	<i>SCREWING TIME</i>	<i>SCREWING COUNT</i>
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<i>TORQUE</i>	<i>ANGLE</i>	<i>NOTICE</i>
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Result = screw evaluation: correct or incorrect.

OK = the torque has been correctly reached, all the selected parameters are satisfied and the control unit will give out a beep sound of 0.5 sec.

NOK = the torque has been reached during the ramp time or the fast speed (see error table). In this case, the unit will give out 2 beep sounds and the red led will light up.

Screwdriver model = model of selected screwdriver.

% Torque = percentage of the set torque level.

S: Speed = speed value.

ST: Screwing time = it indicates the time of the screwing.

Screws Count = number of screws screwed/number of total screws of the sequence/ program.

T: Torque = torque value.

A: Angle = angle value.

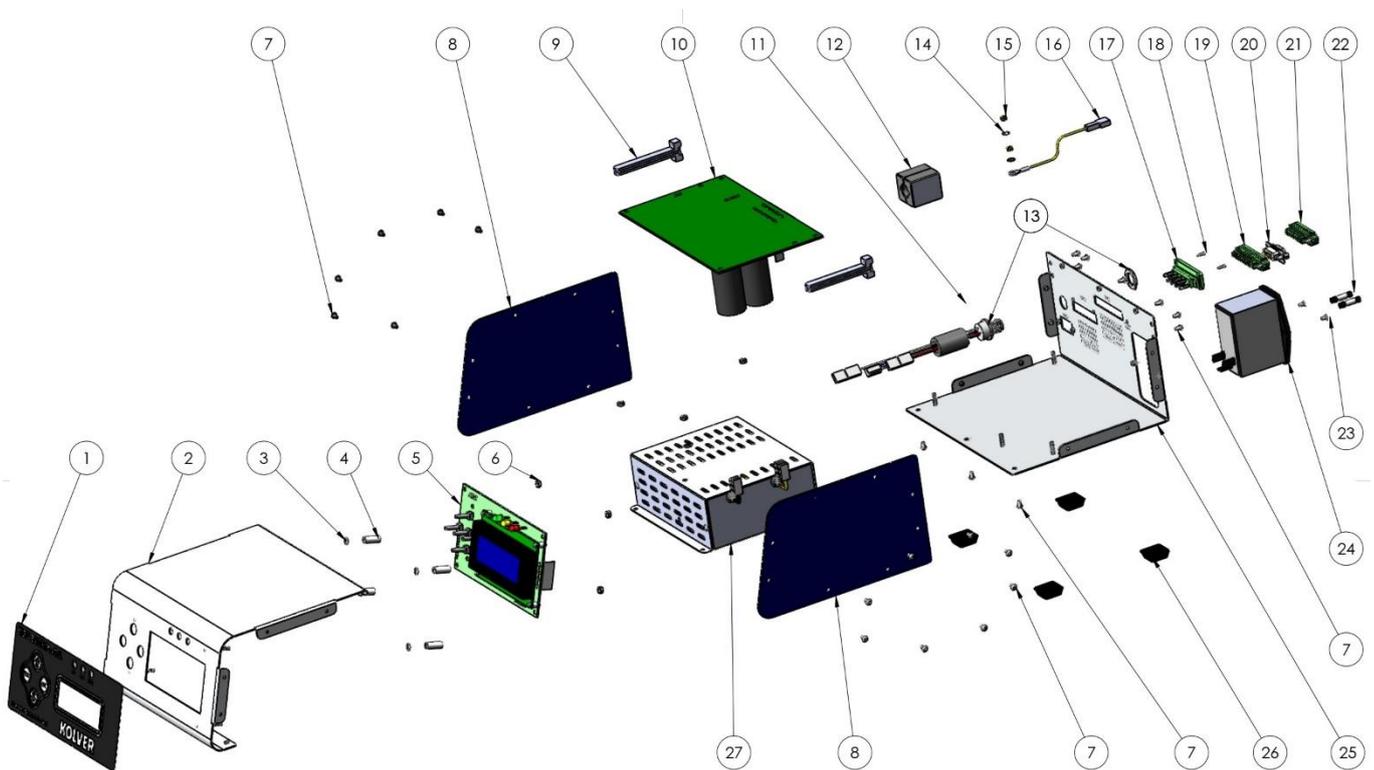
Notice = in case of program end, it prints “Program End” or it indicates the type of error (see paragraph: trouble shooting).

Example of serial print:

```

OK PLUT03  Tz:20% S:1300rpm ST: 0.7s Screw:01/01 T:69.59 Nm A: 4957deg Program end
OK PLUT03  Tz:20% S:1300rpm ST: 0.7s Screw:01/01 T:70.02 Nm A: 4776deg Program end
OK PLUT03  Tz:20% S:1300rpm ST: 0.5s Screw:01/01 T:69.17 Nm A: 3505deg Program end
NOK PLUT03  Tz:20% S:1300rpm ST: 0.0s Screw:00/01 T:71.72 Nm A: 78deg Error min time
OK PLUT03  Tz:20% S:1300rpm ST: 0.5s Screw:01/01 T:69.59 Nm A: 3299deg Program end
OK PLUT03  Tz:20% S:1300rpm ST: 0.4s Screw:01/01 T:69.38 Nm A: 2289deg Program end
NOK PLUT03  Tz:20% S:1300rpm ST: 0.1s Screw:00/01 T:--- A: 720deg Error ang. max
NOK PLUT03  Tz:20% S:1300rpm ST: 0.4s Screw:00/01 T:--- A: 2720deg Error ang. max
OK PLUT03  Tz:20% S:1300rpm ST: 0.4s Screw:01/01 T:69.38 Nm A: 2399deg Program end
OK PLUT03  Tz:20% S:1300rpm ST: 0.3s Screw:01/01 T:69.17 Nm A: 2012deg Program end
NOK PLUT03  Tz:20% S:1300rpm ST: 0.3s Screw:00/01 T:69.17 Nm A: 2194deg Err. under min angle
  
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EXPLODED VIEW EDU2AE/HPRO/TA



SPARE PARTS

Position	Description	Qty	Code
1	FRONT MEMBRANE HPRO/TA (BLACK)	1	858004
2	FRONT PANEL EDU2AE/HPRO	1	818015
3	WASHER M3	8	800042
4	SPACER 15mm	4	890004/T
5	DISPLAY BOARD	1	852522
6	NUT M3	7	800056
7	SCREW M3 X 5 ZN TX10	22	872444
8	SIDE EDU 2AE/HPRO (BLUE)	2	818013
9	BOARD SUPPORT	2	872442
10	MAIN BOARD	1	852521/SW
11	FLAT	1	872438
12	FERRITE	1	872468
13	CONNECTOR M 8 PIN + FERRITE	1	201766/LTA
14	WASHER	4	800041
15	BRASS NUT M3 OTTONE	2	800056/O
16	GROUND CABLE	1	800090/E
17	8 PIN M CONNECTOR	1	872457
18	SCREW M2 X 4	2	801004
19	I/O 10 PIN F CONNECTOR	1	800102
20	SERIAL F CONNECTOR	1	890005/F
21	8 PIN F CONNECTOR	1	872464
22	FUSE 3,15A	2	800619
23	SCREW M3X5 TX10	2	801003
24	FILTER R13.6A	1	800718

25	BOTTOM PANEL	1	818014
26	RUBBER SUPPORT	4	800016-B
27	SWITCHING	1	872490

GUARANTEE

1. This KOLVER product is guaranteed against defective workmanship or materials, for a maximum period of 12 months following the date of purchase from KOLVER, provided that its usage is limited to single shift operation throughout that period. If the usage rate exceeds of single shift operation, the guarantee period shall be reduced on a prorata basis.
2. If, during the guarantee period, the product appears to be defective in workmanship or materials, it should be returned to KOLVER or its distributors, transport prepaid, together with a short description of the alleged defect. KOLVER shall, at its sole discretion, arrange to repair or replace free of charge such items.
3. This guarantee does not cover repair or replacement required as a consequence of products which have been abused, misused or modified, or which have been repaired using not original KOLVER spare parts or by not authorized service personnel.
4. KOLVER accepts no claim for labour or other expenditure made upon defective products.
5. Any direct, incidental or consequential damages whatsoever arising from any defect are expressly excluded.
6. This guarantee replaces all other guarantees, or conditions, expressed or implied, regarding the quality, the marketability or the fitness for any particular purpose.
7. No one, whether an agent, servant or employee of KOLVER, is authorized to add to or modify the terms of this limited guarantee in any way. However it's possible to extend the warranty with an extra cost. Further information at kolver@kolver.it.